

Calibrations III

Exceptional Geom's

\mathbb{R} = real nos. \mathbb{C} = complex nos \mathbb{H} = quaternions \mathbb{O} = octonions

In all cases: $\langle \cdot, \cdot \rangle$ and $\bar{\quad} : F \rightarrow F$ involution.

$$(1) \quad |xy| = |x||y|$$

$$(2) \quad \langle zx, y \rangle = \langle x, \bar{z}y \rangle$$

$$(3) \quad \overline{xy} = \bar{y}\bar{x} \quad \text{and} \quad |x|^2 = x\bar{x} = \bar{x}x$$

\mathbb{H} is not commutative

\mathbb{O} " " associative.

Theorem (Artin) The subalgebra with 1: $\langle 1, x, y \rangle$, generated by any two elements $x, y \in \mathbb{O}$ is associative.

(in fact contained in a quaternion subalgebra of \mathbb{O}).

Moufang Identities:

$$(xyx)z = x(y(xz))$$

$$z(xy x) = ((zx)y)x$$

$$(xy)(zx) = x(yz)x$$

Cayley-Dickson Process

A = an algebra with $(\bar{\quad})$.

Define mult. on $A \oplus A$ by:

$$(a, b) \cdot (c, d) = (ac - \bar{d}b, da + b\bar{c})$$

$$\overline{(a, b)} = (\bar{a}, -b)$$

This generates recursively

$$\mathbb{R} \rightarrow \mathbb{C} \rightarrow \mathbb{H} \rightarrow \mathbb{O}$$

Cross Products on \mathbb{H}

$$x \times y \equiv -\frac{1}{2} (\bar{x}y - y\bar{x})$$

$$x \times y \times z \equiv \frac{1}{2} \{ x(\bar{y}z) - z(\bar{y}x) \}$$

$$x \times y \times z \times w \equiv \frac{1}{4} \left\{ \bar{x}(y \times z \times w) + \bar{y}(z \times x \times w) + \bar{z}(x \times y \times w) + \bar{w}(y \times z \times x) \right\}$$

or alt of the

• Each form is alternating (skew)

★ • $|x \times y| = |x \wedge y|$, $|x \times y \times z| = |x \wedge y \wedge z|$, $|x \times y \times z \times w| = |x \wedge y \wedge z \wedge w|$

Idea In each case $\text{Re}(\cdot)$ is a calibration
 $\text{Re}(\cdot) = \pm 1 \Leftrightarrow \text{Im}(x) \equiv x' = 0$
the eqns

$$\text{Re}(x \times y) = 0$$

$$\text{Re}(x \times y \times z) = \langle x', y'z' \rangle \quad \text{for } x, y, z \in \text{Im } \mathbb{H}$$

$$\text{Re}(x \times y \times z \times w) = \langle x, y \times z \times w \rangle$$

$x, y, z, w \in \text{Im } \mathbb{H}$

$$\text{Im}(x \times y) = \frac{1}{2} [x, y]$$

commutator.

$$\text{Im}(x \times y \times z) = \frac{1}{2} [x, y, z]$$

associator

$$\text{Im}(x \times y \times z \times w) = \frac{1}{2} [x, y, z, w]$$

coassociator.

$$[x, y] \equiv xy - yx$$

$$[x, y, z] = (xy)z - x(yz)$$

$$-\frac{1}{2} [xyzw] = \langle y, zw \rangle x + \langle z, xw \rangle y + \langle x, yw \rangle z + \langle y, xz \rangle w$$

Associative Geometry

$$\mathbb{R}^7 = \text{Im } \mathbb{O}$$

Def

$$\varphi(x, y, z) = \langle x, y \cdot z \rangle$$

associative calibration

φ is alternating

$$|\varphi(e_1, e_2, e_3)| \leq |\langle e_1, e_2 \cdot e_3 \rangle| \leq |e_1| |e_2 \cdot e_3| = 1$$

$$"=" \iff e_i = e_j \cdot e_k \quad (+ \text{permutations})$$

$\iff \text{span}\{1, e_1, e_2, e_3\}$ is a H -subalgebra

$$|\varphi(x, y, z)| + \frac{1}{4} |[x, y, z]|^2 = |x \wedge y \wedge z|^2$$

$$|\varphi(x, y, z)| = |x \wedge y \wedge z| \iff [x, y, z] = 0$$

$\mathcal{G}(\varphi) =$ the set of can. or'd
 Im-parts of \mathbb{H} -subalg's
 of $\text{Im} \mathbb{O}$.
 = 3-planes on which $[\cdot, \cdot] = 0$

The associative 3-planes

$$G_2 \equiv \text{Aut}(\mathbb{O})$$

$$G_2 = \{g \in O_7 : g^* \varphi = \varphi\} \quad \leftarrow \text{see def of } \varphi.$$

$$\mathcal{G}(\varphi) \cong G_2 / SO_4$$

$SO_4 = Sp_1 \times Sp_1 / \mathbb{Z}_2$ acts on $\text{Im} \mathbb{O} = \text{Im} \mathbb{H} \oplus \mathbb{H}$ by
 $T_{(g, h)}(u, v) = (gu\bar{h}, p v \bar{h})$.

Associative submanifolds:

$$M^3 \subset \mathbb{R}^7 = \text{Im} \mathbb{O} \quad \text{or'd}$$

$$T_x M^3 \in \mathcal{G}(\varphi) \quad \forall x \in M$$

Diff Eq Express M (locally)
as a graph of

$$f: \Omega \rightarrow \mathbb{H}^1$$

$$\Omega \text{ open} \subset \text{Im} \mathbb{H} \quad \text{and} \quad \text{Im} \mathbb{H} = \text{Im} \mathbb{H} \oplus \mathbb{H}k$$

Thm $\text{gr}(f)$ is associative \Leftrightarrow

$$\boxed{Df = \sigma f}$$

where

$$Df = - \frac{\partial f}{\partial x_1} i - \frac{\partial f}{\partial x_2} j - \frac{\partial f}{\partial x_3} k \quad \text{Dirac}$$

$$\sigma f = \frac{\partial f}{\partial x_1} \times \frac{\partial f}{\partial x_2} \times \frac{\partial f}{\partial x_3}$$

Pf Suffices to consider f linear

$$Df = -f(x)i - f(y)j - f(z)k$$

$$\sigma f = f(x) \times f(y) \times f(z)$$

Calculation shows: $x = i + f(x)$, $y = j + f(y)$, $z = k + f(z)$

$$\frac{1}{2} [x, y, z] = \text{Im}(x \times y \times z)$$

$$= (T, \sigma(f) - D(f)) \in \text{Im}(\mathbb{H} \oplus \mathbb{H})$$

"
Im ①

① $\text{gr}(f)$ is assoc.

$$\Leftrightarrow [x, y, z] = 0$$

$$\Rightarrow \sigma(f) = D(f)$$

② $\sigma(f) = D(f) \Rightarrow [x, y, z] \in \text{Im } \mathbb{H}$

But $[x, y, z] \perp x \perp y$ and $\perp z$.

$\text{Im } \mathbb{H}$ comp's of x, y, z are z, j, k

$$\therefore [x, y, z] = 0$$

and $\text{gr}(f)$ is assoc.

qed (up to orientation)

Existence:

Thm $B^2 \subset \mathbb{I}m \textcircled{1}$ any C^∞ submanifold. Then $\exists!$ (germ) associative 3-man. $M^3 \supset B$.

PF C-K

Coassociative Geom

Def $\psi \in \Lambda^4 \mathbb{I}m \textcircled{1}$

$$\psi(x, y, z, w) \equiv \frac{1}{2} \langle x, [y, z, w] \rangle$$

coassociative calibration

We have

$$\psi(x, y, z, w)^2 + \frac{1}{4} |[x, y, z, w]|^2 = |x \wedge y \wedge z \wedge w|^2$$

★ ψ is a calibration and
 $\psi(x, y, z, w) = 1 \iff [x, y, z, w] = 0$

Calculation

$$\psi = * \psi$$

$$\therefore \mathcal{G}(\psi) \xrightarrow{\approx} \mathcal{G}(\psi)$$

$$\mathbb{E} \longmapsto * \mathbb{E} = \text{"}\mathbb{E}^\perp\text{"}$$

Coassociative 4-planes.

Prop $\mathbb{E} = 4\text{-plane in } \text{Im } \mathbb{H}$

$\pm \mathbb{E}$ is coassociative $\Leftrightarrow x \cdot y \perp \mathbb{E}$
 $\forall x, y \in \mathbb{E}$

The equation

$$F : \Omega \rightarrow \text{Im } \mathbb{H}$$

$$\Omega^{\text{open}} \subset \mathbb{H}$$

Write

$$F = F_1 i + F_2 j + F_3 k$$

F_k are \mathbb{R} -values

Consider:

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$$\hat{D}F = -\nabla F_1 \cdot i - \nabla F_2 \cdot j - \nabla F_3 \cdot k$$

$$\hat{\sigma}F = \nabla F_1 \times \nabla F_2 \times \nabla F_3$$

where ∇F_i is considered in \mathbb{H}

Thm $\text{gr}(F)$ is coassociative

$$\Leftrightarrow \boxed{\hat{D}F = \hat{\sigma}F}^*$$

Cor C^1 sol^{ns} of $*$ are C^ω .

Interesting Example Fix unit vector
 $u \in \text{Im } \mathbb{H}$

$$H: S^3 \rightarrow S^2$$

$$H(q) = \frac{\sqrt{5}}{2} \bar{q} u q. \quad \begin{array}{l} q \in \mathbb{H} \\ |q| = 1 \end{array}$$

Thm The cone on $\text{gr}(H)$ is co-associative.

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i.e. The graph of $h: \mathbb{H} \rightarrow \text{Im}(\mathbb{H})$

$$h(q) = \frac{\sqrt{5}}{3} \frac{1}{\|q\|} \bar{q} u q.$$

is absolutely val. min.

(Lipschitz but not C^1)
Osserman.

Cayley Geometry

$$\underline{\Phi} \in \Lambda^4 \mathbb{O}^*$$

Def

$$\underline{\Phi}(x, y, z, w) = \langle x, y \times z \times w \rangle$$

Cayley 4-form.

Thm

$$\underline{\Phi}(x, y, z, w)^2 + |\operatorname{Im}(x \times y \times z \times w)|^2 = |x, y, z, w|^2$$

Cor

$\underline{\Phi}$ is a calibration and $\pm \xi = x, y, z, w$
is a $\underline{\Phi}$ -plane $\Leftrightarrow \operatorname{Im}(x \times y \times z \times w) = 0$.

$\mathcal{L}(\underline{\Phi}) =$ "the Cayley 4-planes"

$$\cong \operatorname{Spin}(7) / K$$

$$K = \operatorname{SU}_2 \times \operatorname{SU}_2 \times \operatorname{SU}_2 / \mathbb{Z}_2$$

Fact

$$\underline{\Phi} = 1 \wedge \psi + \psi.$$

Other characterizations (of Cayley 4-planes)

* $\mathbb{M} \in G_4(\mathbb{O})$ is a Cayley 4-plane

$$\iff xxyxz \in \mathbb{M} \quad \forall x, y, z \in \mathbb{E}$$

$$\iff \mathbb{M} \text{ is } \mathbb{O} \text{ wrt every } \mathbb{O}\text{-structure } J_{xxy} \text{ on } \mathbb{O} \text{ for all } x, y \in \mathbb{E}$$

$$\iff \omega|_{\mathbb{M}} \text{ is } \underline{\text{antiself dual}}$$

where $\omega \equiv$ Kahler form for J_e

$$\mathbb{O} \equiv \mathbb{H} \oplus \mathbb{H} \cdot e$$

Note

$$\Phi = -\frac{1}{2} \omega \lrcorner \omega + \text{Re}\{dz\}$$

for J_e .

The Cayley Eqⁿ

Cay³

$$\Omega_{\text{open}} \subset \mathbb{H}$$

$$f: \Omega \rightarrow \mathbb{H}$$

Define 3 operators e_1, \dots, e_4 any or. o.n. basis of \mathbb{H}

1. Dirac Operator

$$\begin{aligned} Df &\equiv \sum_{j=1}^4 (\nabla_{e_j} f) \bar{e}_j \\ &= \frac{\partial f}{\partial x_0} - \frac{\partial f}{\partial x_1} \cdot i - \frac{\partial f}{\partial x_2} \cdot j - \frac{\partial f}{\partial x_3} \cdot k \end{aligned}$$

$$\left(\begin{array}{l} \text{also } -\bar{D}f = \frac{\partial f}{\partial x_0} + \frac{\partial f}{\partial x_1} i + \frac{\partial f}{\partial x_2} j + \frac{\partial f}{\partial x_3} k \\ D\bar{D} \neq \bar{D}D = +\Delta \end{array} \right)$$

$$2. \quad \sigma f \equiv \sum_{d_1 < d_2 < d_3} \{ (\nabla_{e_{d_1}} f) \times (\nabla_{e_{d_2}} f) \times (\nabla_{e_{d_3}} f) \} \overline{(e_{d_1} \times e_{d_2} \times e_{d_3})}$$

$$3. \quad \delta f \equiv \sum_{j_1 < j_2} \{ (\nabla_{e_{j_1}} f) \times (\nabla_{e_{j_2}} f) \} \overline{(e_{j_1} \times e_{j_2})}$$

Thm Graph(f) is Cayley \Leftrightarrow $\begin{array}{l} Df = \sigma f \\ \text{and} \\ \delta f = 0 \end{array}$

\checkmark If $\det(df) \neq 1$, $\delta f = 0$ automatically

Special Case: Write

$$f = +\bar{D}g. \quad g: \Omega \rightarrow \mathbb{H}$$

Then

$$\boxed{\Delta g = \sigma(\bar{D}g)}$$

is The Cayley equation

Implicit P^n Techniques Apply.

Globalize to Manifolds

GM!

$G \subset O_n$ Lie-subgroup

Def A G -manifold is a riemannian n -manifold with holonomy group $\subseteq G$. (conv. class)

SU_m -man.'s
(Ricci-flat Kähler)
"Calabi-Yau"

G_2 -man.'s
($n=7$)

$Spin_7$ -manifolds
($n=8$)

Slag sub.'s

Assoc.
sub.'s

Coassoc.
sub.'s

Cayley
sub.'s.

I) SU_m -holon.
on \mathbb{C} -man.

$\omega =$ Kähler form
 $\Phi =$ parallel $(0,n)$ -form.

$$\varphi \equiv \operatorname{Re} \Phi$$

has $\operatorname{comass} \equiv 1$ and $d\varphi = 0$ ($\nabla\varphi = 0$).

II) $\varphi \in \mathcal{E}^3$
parallel assoc.
cal.

$\psi = * \varphi$
parallel assoc.
cal.

III) $\Phi \in \mathcal{E}^4$ parallel

Q12

Remember $\varphi \in \Lambda^p T_x X$ is fixed by holon. G_x

$\Leftrightarrow \varphi$ has a parallel extension to X .

(In $G_2, Spin_7$ -cases, φ, Φ determine the Riem. structure and $d_{\varphi} \varphi = 0 \Leftrightarrow d\varphi = 0$ - -)

Deformations of compact
 φ -submanifolds

Slag. Case $M^m \subset X$ opt Slag in SU_m -manifold.

Theorem: The moduli space of all S.L. submanifolds in a C^1 -nbhd of M is a C^ω man. of dimension $b_1(M)$.
It's Tang space is naturally identified with $H^1_M = \text{harm } \varphi_1\text{-forms}$.

Deformations of sp. Lagrangian

$M \subset X$ S-Lag., cpt oriented.

$$T^*M \cong TM \cong NM \cong N^*M.$$

① Fix nbhd U of $M \subset N(M) \cong \mathbb{R}$.

$$\exp: U \rightarrow X$$

is a diffeo. onto an open set $\hat{U} \subset X$.

② Any section $V \in \Gamma(N)$ gives an embedded sub. $M_V = \exp(V) \subset U$, and every sub. in a C^1 -nbhd of M is of this form.

③ M_V is S-Lag $\Leftrightarrow \omega|_{M_V} = \psi|_{M_V} = 0$
 $\Leftrightarrow \exp(V)^*\omega = \exp(V)^*\psi = 0$

Consider the map

$$\mathcal{E}^1(M) = \Gamma(N) \xrightarrow{\Psi} \Omega^2(M) \oplus \mathcal{E}^n(M)$$

$$V \longmapsto (\exp(V)^*\omega, \exp(V)^*\psi)$$

④ $\Psi^{-1}(0) \cap \mathcal{U} \cong$ all S-Lag submans in \mathcal{U} .

We now compute $d\psi|_0$.

GMK
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Fix $V \in \Gamma(N)$ and $x \in M$.

Choose o.n. frame field

$e_1, \mathcal{J}e_1, \dots, e_n, \mathcal{J}e_n$ near x

s.t.

(i) Along M e_1, \dots, e_n are tangent to M
($\mathcal{J}e_1, \dots, \mathcal{J}e_n$ - normal ..)

$$(ii) (\nabla_{e_i} e_j)|_x = 0$$

Let $\omega_1, \mathcal{J}\omega_1, \dots, \omega_n, \mathcal{J}\omega_n$ be dual coframe.

$$\left(\begin{array}{l} (i) \Rightarrow \omega_1, \dots, \omega_n|_M \text{ dual to } e_1, \dots, e_n \\ \mathcal{J}\omega_1, \dots, \mathcal{J}\omega_n|_M = 0 \end{array} \right)$$

$$\left[\begin{array}{l} \omega = \sum_{j=1}^n \omega_j \wedge \mathcal{J}\omega_j \\ \psi = \prod_{m=1}^n (\omega_1 + i\mathcal{J}\omega_1) \wedge \dots \wedge (\omega_n + i\mathcal{J}\omega_n) \end{array} \right.$$

We want to compute:

$$\frac{d}{dt} \exp(tV)^*(\omega) \Big|_{t=0}$$

$$\frac{d}{dt} \exp(tV)^*(\psi) \Big|_{t=0}$$

$$V = \sum V_k J e_k \approx \sum V_k e_k \approx \sum V_k \omega_k.$$

$$\begin{cases} \exp(tV)^*(\omega_k) = \omega_k + O(t) \\ \exp(tV)^*(J\omega_k) = (dV_k)t + O(t^2) \quad \underline{\text{at } x} \end{cases}$$

$$dV_k = \sum_{j=1}^n V_{kj} \omega_j \quad V_{kj} = e_j \cdot V_k$$

$$\stackrel{ii}{\Rightarrow} \exp(tV)^*(\omega) = \sum_{k=1}^n \omega_k \wedge \left(\sum_{j=1}^n V_{kj} \omega_j \right) \cdot t + O(t^2)$$

$$= t dV + t^2$$

$$\begin{aligned} (dV) &= \sum \omega_j \wedge \nabla_{e_j} V = \sum \omega_j \wedge \nabla_{e_j} \sum V_n \omega_n \\ &= \sum \omega_j \wedge \sum V_{nj} \omega_n = \sum V_{nj} \omega_j \wedge \omega_n \end{aligned}$$

$$\exp(tV)^*(\psi) = \text{Im} \left\{ \prod_{k=1}^n \left(\omega_k + it \sum_{j=1}^n V_{kj} \omega_j \right) \right\} + \dots$$

$$= \text{Im} \left\{ (\omega_1 + it \sum V_{1j} \omega_j) \dots (\omega_n + it \sum V_{nj} \omega_j) \right\}$$

$$= t \left(\sum_{j=1}^n V_{dj} \right) \omega_1 \wedge \dots \wedge \omega_n + O(t^2)$$

$$= t * (d^* V) + O(t^2)$$

$$\begin{aligned}
 *d^*V &= d(*V) \\
 &= \sum_{j=1}^n \omega_j \wedge \nabla_{\omega_j} \left(\sum_{k=1}^n V_k(t) \omega_1 \wedge \dots \wedge \hat{\omega}_k \wedge \dots \wedge \omega_n \right) \\
 &= \sum_{j=1}^n V_{d_j} (\omega_1, \dots, \omega_n).
 \end{aligned}$$

Prop

$$\Gamma(N) \xrightarrow{d\Psi_0} \mathcal{E}^2(M) \oplus \mathcal{E}^n(M)$$

\parallel ||

$$\mathcal{E}^1(M) \xrightarrow{(-d, *d^*)} \mathcal{E}^2(M) \oplus \mathcal{E}^n(M)$$

$$\text{Ker}(d\Psi_0) = H^1 = \text{harm } 1\text{-forms.}$$

Now Use the Implicit F² Thm in Banach Spaces.

$$\textcircled{\text{I}} \quad \Psi: \mathcal{E}^1(M) \rightarrow d\mathcal{E}^1(M) \oplus d\mathcal{E}^{n-1}(M)$$

i.e. $\exp(*V)^*(\alpha)$ and $\exp(*V)^*(\psi)$ are exact.

PF

$\exp(V)$ is homotopic

to $f: M \subset X$ and $f^* \omega = f^* \psi = 0$.

$$\therefore [\exp(V)^* \omega] = [f^* \omega] = 0$$

$$[\text{---} \psi] = [f^* \psi] = 0$$

in $H_{\text{deR}}(M)$ \square

Now

$$\mathcal{E}^1(M)_{C^{1,d}} \xrightarrow{\underline{\Psi}} d \mathcal{E}^1(M)_{C^{0,d}} \oplus d \mathcal{E}^{n-1}(M)_{C^{0,d}}$$

a bounded map of Banach manifolds

$$\text{i.e. } \mathcal{E}^1(M)_{C^{1,d}} \xrightarrow{\underline{\Psi}} \mathcal{E}^2(M)_{C^{0,d}}^{\text{exact}} \oplus \mathcal{E}^n(M)_{C^{0,d}}^{\text{exact}}$$

and $d\underline{\Psi}_0 = (-d, *d^*)$

is an isomorphism.

IFIM $\Rightarrow \underline{\Psi}^{-1}(0)$ is a submanifold of
 $\dim = \dim \mathbb{R}^{-1}(M/\mathbb{R})$

Similar Result in Coassoc. Case.

Tang space \cong Anti-self dual
Harm 2-forms.

Assoc. Case

\exists Right Cliff Mult by Tang vectors
on normal bundle

$\therefore \exists$ Dirac op. \mathcal{D}

Tang space $= \ker \mathcal{D}$.

Cayley is similar

Here we do not know
about mod. space

Spinors and Calibrations

For simplicity $V = \mathbb{R}^{2k}$ with $\langle \cdot, \cdot \rangle = \text{standard}$

$$\begin{aligned} \text{Cl}(V) &\equiv \text{Cliff alg of } (V, \langle \cdot, \cdot \rangle) \\ &= \{1, e_1, \dots, e_{2k} : e_i e_j + e_j e_i = -2\delta_{ij} \mathbb{1}\} \\ &\cong \Lambda^* V \text{ as } \underline{V\text{-spaces}}. \end{aligned}$$

Basic Fact $\text{Cl}(V) = \text{End}_{\mathbb{R}}(S)$

where $S \cong \mathbb{R}^{16^k}$ is the (real) spinor space

I. \exists inner prod. $\langle \cdot, \cdot \rangle_S$ on S

$$\langle e\sigma_1, e\sigma_2 \rangle_S = \langle \sigma_1, \sigma_2 \rangle \quad \forall e \in V \quad |e|=1$$

II. \exists inner prod $\langle \cdot, \cdot \rangle_{\text{cl}}$ on Cl

$$\langle A, B \rangle_{\text{cl}} = \text{tr}_S A^* \cdot B$$

III. \exists inner prod $\langle \cdot, \cdot \rangle_{\Lambda^*}$ on Λ^* (standard L^2)

Lemma $\langle A, B \rangle_{\text{cl}} = 16^k \langle A, B \rangle_{\Lambda^*}$

PF $\langle A, B \rangle_{\text{cl}} = \sum_{\alpha=1}^{16^k} \langle A(\sigma_\alpha), B(\sigma_\alpha) \rangle_S$

any unit vector. $\langle e_{i_1} \dots e_{i_p}, e_{i_1} \dots e_{i_p} \rangle_{\text{cl}} = \sum_{\alpha} \dots = \sum_{\alpha} \langle \sigma_\alpha \sigma_\alpha \rangle = 16^k$

OTL 2.

Main Principle The square of a spinor yields interesting calibrations.

Given $\sigma \in S$, $(|\sigma| = 1)$, define $\sigma \cdot \sigma \in Cl$

by
$$\boxed{\sigma \cdot \sigma(\tau) \equiv \langle \tau, \sigma \rangle \sigma}$$

Lemma Given $\varphi \in Cl$

$$\boxed{\langle \varphi, \sigma \cdot \sigma \rangle_{Cl} = \langle \sigma, \varphi \cdot \sigma \rangle_S}$$

PF
$$\begin{aligned} \langle \varphi, \sigma \cdot \sigma \rangle_{Cl} &= \text{tr}(\varphi^t \cdot (\sigma \cdot \sigma)) \\ &= \sum_{\alpha} \langle \varphi(\sigma_{\alpha}), (\sigma \cdot \sigma)(\sigma_{\alpha}) \rangle_S \end{aligned}$$

Choose $\sigma_1 \dots \sigma_{16^k}$; $\sigma_i = \sigma$ $= \langle \varphi(\sigma), \sigma \rangle_S$ qed.

Now under $Cl(V) \cong \Lambda^* V$ decompose

$$\# \sigma \cdot \sigma \equiv \sum_{p=0}^n \psi_p \quad \begin{array}{l} n = 8k \\ N = 16^k \end{array}$$

Thm Each ψ_p is a calibration

Pf $\xi \in \wedge^p V$ a unit simple vector

$$\langle \xi, \sigma \cdot \sigma \rangle_{ce} = \langle \sigma, \xi \sigma \rangle \leq \|\sigma\| \|\xi \sigma\| = 1$$

"

$$N \langle \xi, \sigma \cdot \sigma \rangle_{\wedge}$$

"

$$\langle \xi, N \sigma \cdot \sigma \rangle_{\wedge} \quad \text{qed.}$$

Can see many things:

① $\mathcal{G}(\mathcal{U}_p) = \{ \xi : \xi \sigma = \sigma \}$.

② $\text{Spin}_n \xrightarrow{\mathbb{Z}_2} \text{SO}_n$ acts on S
 $G_{\sigma} = \{ g \in \text{Spin}_n : g \sigma = \sigma \}$.

Then G_{σ} acts on $\mathcal{G}(\mathcal{U}_p) \quad \forall p$.

Ex $k=1 \quad S = S^+ \oplus S^-$

$V \quad \begin{matrix} S^+ \\ S^- \end{matrix} \quad \text{all } \mathbb{R}^d$

3 reps of Spin_8

Triality etc

Spin₈ is transitive on unit vectors in each.

Choose $\sigma \in S^+$ $|\sigma| = 1$

$$16 \sigma \circ \sigma = 1 + \Phi + *1$$

↙ Cayley calibration

Spin₇ - fixes σ
∴ acts on $\Lambda(\Phi)$.

So on manifolds

Parallel spinors square to give
interesting calibrations.

