

Jonathan Mattingly

Lecture 1

$\{u_t : t \geq 0\}$ $u_t \in X \leftarrow$ Polish space
 \mathcal{E} - a σ -algebra.

t here may be cts or discrete.

Markov Processes $P(u_0, A) = P(u_t \in A | u_0)$

$P: X \times \mathcal{E} \rightarrow [0, 1]$

Markov transition kernel

$x \mapsto P(x, \cdot)$ is a probability measure

$A \mapsto P(\cdot, A)$ is a measurable function

\uparrow prob u_t is in space
A given initial data u_0 .

$\Phi: X \rightarrow \mathbb{R}$

$$(\mathcal{P}\Phi)(x) = \int_X \Phi(y) P(x, dy)$$

\hookrightarrow some real-valued statistic of state space \mathcal{P} action on Φ

If μ is a probability measure

$\mu \in \mathcal{M}(X)$ then define $(\mu \mathcal{P})(A) := \int_{A \in \mathcal{E}} P(x, A) \mu(dx)$

Let $X = \{1, \dots, M\}$. Then $P_{ij} = P(u_1 = j | u_0 = i)$

$\Phi = \begin{pmatrix} \Phi(1) \\ \vdots \\ \Phi(M) \end{pmatrix}$, $\mathcal{P}\Phi \leftarrow$ just matrix multiplication, $\mu = (\mu(1), \dots, \mu(M))$
 $\mu \mathcal{P} \leftarrow$ left multi of matrix

$P_m := \underbrace{P \dots P}_m$ m times, $P_{n+m} = P_n P_m = P_n P_m$

$P_t \Phi = \mathbb{E}_{u_0=x} \Phi(u_t) = \mathbb{E}(\Phi(u_t) | u_0 = x)$

μ is invariant (stationary) if $\mu P = \mu$
 alternatively $\mu P f = \mu f$ for all bdd cts f

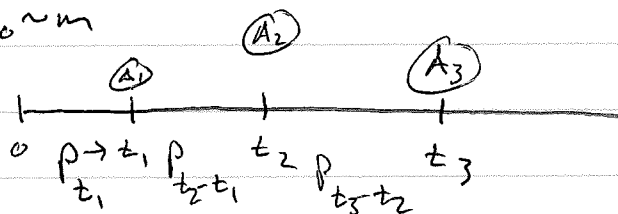
$$X^{\mathbb{N}} := \{ (x_0, x_1, \dots) : x_i \in X, i \in \mathbb{N} \}$$

$x = (x_0, x_1, \dots) \in X^{\mathbb{N}}$. Let m be a measure on X .

Define $m P_{\mathbb{N}}$ as a measure on $X^{\mathbb{N}}$.

↳ done through the Kolmogorov ext. thm.

$x_0 \sim m$



What's the prob of being in A_1 at t_1 , A_2 at time t_2 , and ~~A_3~~ at time t_3 ? What is the measure of this set?

$$m P_{\mathbb{N}}(A) = \int_{X \times A_1 \times A_2 \times A_3} m(dx_0) P_{t_1}^{t_1}(x_0, dy_1) \cdot P_{t_2}^{t_2, t_1}(y_1, dy_2) \cdot P_{t_3}^{t_3, t_2}(y_2, dy_3)$$

Now we define a shift operator:

$$\Theta : (x_0, x_1, \dots) \mapsto (x_1, x_2, \dots)$$

Suppose $\Theta : X^{\mathbb{N}} \rightarrow X^{\mathbb{N}}$, a measure M on $X^{\mathbb{N}}$ is invariant if $M \Theta = M(M(\Theta^{-1}(A))) = M(A) \quad \forall A$

$f : X^{\mathbb{N}} \rightarrow \mathbb{R}$ is invariant if $f \Theta^{-1}$ is inv a.s. \hookrightarrow wrt M
 a set A , $\Theta^{-1}(A) = A$ a.s.

Let $(X^{\mathbb{N}}, \Sigma^{\mathbb{N}}, \Theta, M)$,

$\Phi : X^{\mathbb{N}} \rightarrow \mathbb{R}$. Then

1) $\frac{1}{N} \sum_{i=0}^{N-1} \Phi(\Theta^i x) \xrightarrow{M\text{-a.s.}} \bar{\Phi}(x)$ ↑ invariant for Θ

$M = \mu P_{\mathbb{N}}$ ↓ inv measure for P

" $\frac{1}{N} \sum_{i=0}^{N-1} \Phi(x_i)$ " $\Phi(x) = \Phi(x_0)$

2) $\bar{\Phi}$ is Θ inv and $\int \Phi(y) M(dy) = \int \bar{\Phi}(y) M(dy)$

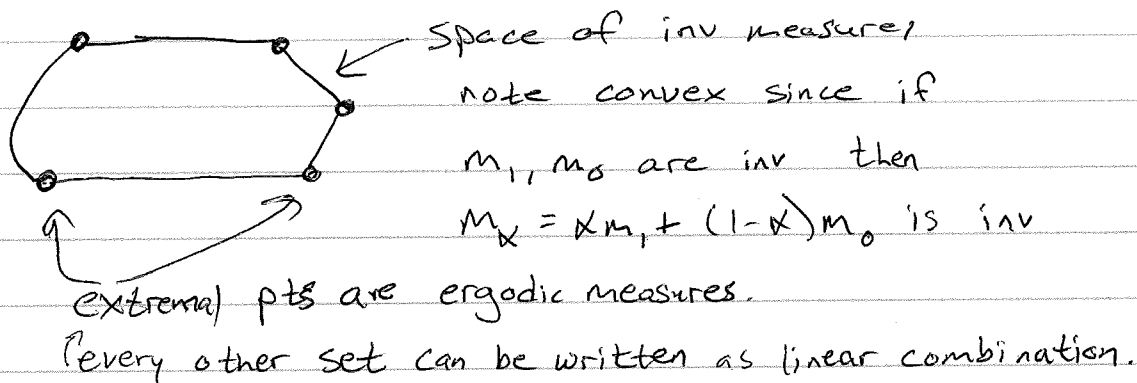
a measure M is ergodic if for any invariant set A , $M(A) \in \{0, 1\}$.

M is ergodic \iff any shift inv Φ is M -a.s. const.

$$\iff \lim_{N \rightarrow \infty} \frac{1}{N} \sum_{n=0}^{N-1} m(A \cap \Theta^{-n} B) = m(A)m(B) \quad \forall A, B$$

Notice $\frac{1}{N} \sum_{n=0}^{N-1} m(A \cap \Theta^{-n} B)$ is $P(x_0 \in A, x_n \in B)$ if A, B are $A \times X \times \dots$ ie a cylinder set

Any invariant measure M is mixture of ergodic invariant measures.



Let m, ν be inv measures

- 1) if m is ergodic and $\nu \ll m \implies m = \nu$
- 2) if m, ν are ergodic, then $m = \nu$ or $m \perp \nu$
- 3) m is an extremal pt iff m is ergodic

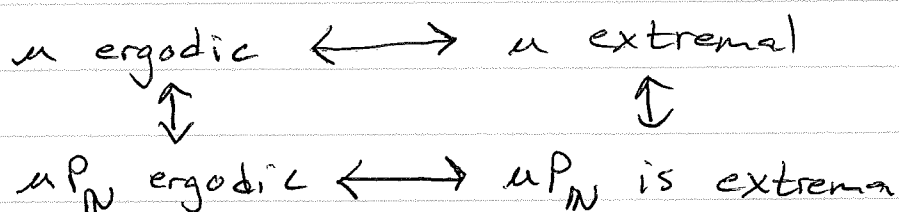
A set A is inv for Markov operator P with inv measure μ ($\mu P = \mu$) if

$$P(X|A) = 1 \quad \mu\text{-a.e. } X \in A$$

$$P(X, A) = 0 \quad \mu\text{-a.e. } X \in A^c$$

μ is ergodic if every inv set A of P with μ inv satisfies $\mu(A) \in \{0, 1\}$.

μ is ergodic $\Leftrightarrow \mu P_N$ is ergodic



$$X = \{1, \dots, N\}$$

Suppose

$$\forall j, \inf_{ij} P_{ij} \geq c_j \geq 0$$

$$\sum c_j > 0$$

$\Rightarrow \exists!$ inv measure

$$\nu = \frac{1}{2} \sum_j c_j \delta_j$$

We will prove this next time

$$X = [0, 1]^N$$

Suppose

$$\inf_{x \in X} P(x, \cdot) \geq x \nu(\cdot)$$

ν a prob measure

$\Rightarrow \exists!$ inv measure