

# The obstacle problem for the fractional Laplacian with drift

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Connections For Women: Harmonic Analysis

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In this talk I will overview this problem and present some new results on the regularity of the free boundary.

# Classical obstacle problem



## Classical obstacle problem



Suppose we want to wrap a meatloaf in a plastic wrap. Here the meatloaf is the **obstacle**, and the configuration of the plastic wrap, after it adjusts to the geometry of the meatloaf, represents the solution to the **obstacle problem**.

## Formulation of the classical obstacle problem

We are given:

- $\phi \in C^2(D)$ , the *obstacle*;
- $\psi \in W^{1,2}(D)$  with  $\phi \leq \psi$  on  $\partial D$ , the *boundary values*;
- $f \in L^\infty(D)$ , the *source term*.

We want to minimize

$$\int_D (|\nabla u|^2 + 2fu) dx$$

over  $\mathcal{K} = \{u \in W^{1,2}(D) : u = \psi \text{ on } \partial D, u \geq \phi \text{ a.e. in } D\}$ .



## Classical obstacle problem

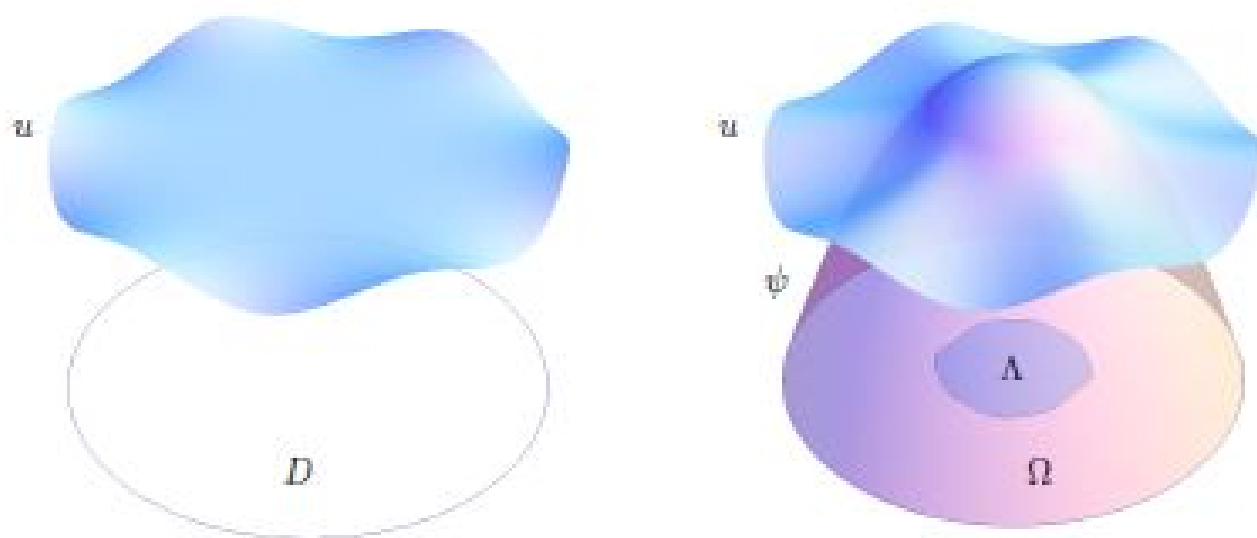


Figure: “Regularity of Free Boundaries in Obstacle-Type Problems”, by Petrosyan, Shahgholian, Uraltseva

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$$\Delta u = f \text{ in } \{u > \phi\}$$

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- **Coincidence set:**  $\Lambda_\phi(u) = \{x \in D \mid u(x) = \phi(x)\}$ .
- **Free boundary:**  $\Gamma_\phi(u) = \partial\{x \in D \mid u(x) = \phi(x)\}$ .

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**First fundamental question:** How smooth is the solution? The optimal regularity of the solution is  $u \in C_{\text{loc}}^{1,1}(D) \cong W_{\text{loc}}^{2,\infty}(D)$ .

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**First fundamental question:** How smooth is the solution? The optimal regularity of the solution is  $u \in C_{\text{loc}}^{1,1}(D) \cong W_{\text{loc}}^{2,\infty}(D)$ .

**Second fundamental question:** How smooth is the free boundary? In 1977 **Kinderlehrer and Nirenberg** proved that, if the free boundary is a  $C^1$  hypersurface, then it is  $C^\omega$  (real analytic). In the same year **Caffarelli** developed his theory of the regularity of the free boundary and proved **Lipschitz** regularity, and then proved how to go from **Lipschitz** to  $C^{1,\alpha}$ .

## Obstacle problem for the fractional Laplacian

We study the obstacle problem defined by the **fractional Laplacian with gradient perturbation**

$$\min\{L\hat{u}(x), \hat{u}(x) - \hat{\varphi}(x)\} = 0, \quad \forall x \in \mathbb{R}^n, \quad (0.1)$$

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where we denote

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The action of  $(-\Delta)^s$  on  $\psi \in C_0^2(\mathbb{R}^n)$  is given by

$$(-\Delta)^s \psi(x) = c_{n,s} \text{ p.v. } \int_{\mathbb{R}^n} \frac{\psi(x) - \psi(y)}{|x - y|^{n+2s}} dy,$$

understood in the sense of the principal value.



## Regularity of the solution

### Assumptions:

- $s \in (1/2, 1)$ ,
- $b \in C^s(\mathbb{R}^n; \mathbb{R}^n)$ ,
- $c \in C^s(\mathbb{R}^n)$  with  $c \geq 0$ ,
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- **existence**,
- **uniqueness** (assuming  $c(x) \geq c_0 > 0$ ,  $\forall x \in \mathbb{R}^n$ , and  $b \in C^{0,1}$ ),
- **optimal regularity of solution**,  $\hat{u} \in C^{1,s}(\mathbb{R}^n)$ .

## Regular set

Here our focus is the *free boundary*, defined as  $\widehat{\Gamma}(\widehat{u}) := \partial\{\widehat{u} = \widehat{\varphi}\}$ .

We will prove regularity of a special subset of  $\widehat{\Gamma}(\widehat{u})$ , the so called *regular set*, denoted by  $\widehat{\Gamma}_{1+s}(\widehat{u})$ .

## Regular set

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The set of regular free boundary points,  $\widehat{\Gamma}_{1+s}(\widehat{u})$ , is, informally, the set of points of  $\widehat{\Gamma}(\widehat{u})$  where the *limit of a frequency function of Almgren type attains its smallest possible value* - formal definition in a few slides :)

## Main result: $C^{1,\gamma}$ regularity of the regular free boundary

Theorem (Garofalo, Petrosyan, Pop & Smit Vega Garcia, 2016)

Let  $s \in (1/2, 1)$ ,  $b \in C^s(\mathbb{R}^n; \mathbb{R}^n)$ ,  $0 \leq c \in C^s(\mathbb{R}^n)$ ,  $\hat{\varphi} \in C^{3s}(\mathbb{R}^n) \cap C_0(\mathbb{R}^n)$ . Let  $\hat{u} \in C^{1,s}(\mathbb{R}^n)$  solve (0.1) and  $x_0 \in \hat{\Gamma}_{1+s}(\hat{u})$ . Then  $\exists \gamma \in (0, 1)$  and  $\eta > 0$ , such that

$$B_\eta(x_0) \cap \hat{\Gamma}(\hat{u}) \subseteq \hat{\Gamma}_{1+s}(\hat{u}),$$

and  $\exists g \in C^{1,\gamma}(\mathbb{R}^{n-1})$ , such that

$$B_\eta(x_0) \cap \hat{\Gamma}(\hat{u}) = B_\eta(x_0) \cap \{x_n \leq g(x')\},$$

after a possible rotation in  $\mathbb{R}^n$ .



## Reduction to an obstacle problem for the fractional Laplacian without drift

We assume  $s \in (1/2, 1)$ ,  $b \in C^s(\mathbb{R}^n; \mathbb{R}^n)$ ,  $0 \leq c \in C^s(\mathbb{R}^n)$ ,  $\hat{\varphi} \in C^{3s}(\mathbb{R}^n) \cap C_0(\mathbb{R}^n)$ .

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Then  $w \in C^{3s}(\mathbb{R}^n)$ . If  $u := \hat{u} - w$  and  $\varphi := \hat{\varphi} - w$ , then  $u$  solves the obstacle problem *without drift*

$$\min\{(-\Delta)^s u(x), u(x) - \varphi(x)\} = 0, \forall x \in \mathbb{R}^n. \quad (0.2)$$

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**Remark:**  $\varphi$  can only be assumed to be in  $C^{3s}(\mathbb{R}^n)$ , even if  $\hat{\varphi}$  is smooth. Notice that  $\Gamma(u) := \partial\{u = \varphi\} = \hat{\Gamma}(\hat{u})$ . We also define  $\Gamma_{1+s}(u) = \hat{\Gamma}_{1+s}(\hat{u})$ .

## Reduction of our main result: $C^{1,\gamma}$ regularity of $\Gamma_{1+s}(u)$

Theorem (Garofalo, Petrosyan, Pop & Smit Vega Garcia, 2016)

Let  $s \in (1/2, 1)$  and  $\varphi \in C^{3s}(\mathbb{R}^n)$ . Let  $u$  solve (0.2) and  $x_0 \in \Gamma_{1+s}(u)$ . Then  $\exists \gamma \in (0, 1)$  and  $\eta > 0$ , such that

$$B_\eta(x_0) \cap \Gamma(u) \subseteq \Gamma_{1+s}(u),$$

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after a possible rotation in  $\mathbb{R}^n$ .

Since  $\widehat{\Gamma}_{1+s}(\widehat{u}) = \Gamma_{1+s}(u)$ , this implies the  $C^{1,\gamma}$  regularity of  $\widehat{\Gamma}_{1+s}(\widehat{u})$ , our main result.

## Literature

Caffarelli, Salsa, Silvestre (2008): assuming  $\varphi \in C^{2,1}(\mathbb{R}^n)$ :  
 $C^{1,\gamma}$  regularity of  $\Gamma_{1+s}(u)$  (case of no drift).



## Literature

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 $C^{1,\gamma}$  regularity of  $\Gamma_{1+s}(u)$  (case of no drift).

Garofalo, Petrosyan, Pop & SVG: assuming  $\varphi \in C^{3s}(\mathbb{R}^n)$ :  
 $C^{1,\gamma}$  regularity of  $\Gamma_{1+s}(u)$  (case of no drift, which implies that  $\widehat{\Gamma}_{1+s}(\widehat{u})$  is also  $C^{1,\gamma}$ ).

## Localize our problem

Let  $a := 1 - 2s$ . Given  $v \in C^2(\mathbb{R}^n \times \mathbb{R}_+)$ , define the operator  $L_a$  as

$$L_a v(x, y) = \operatorname{div}(|y|^a \nabla v)(x, y), \quad \forall (x, y) \in \mathbb{R}^n \times \mathbb{R}_+.$$

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Why are we looking at this operator? If  $L_a w = 0$ , then

$$\lim_{y \downarrow 0} |y|^a w_y(x, y) = -(-\Delta)^s w(x, 0),$$

i.e.,  $(-\Delta)^s$  is a **Dirichlet-to-Neumann map** for the operator  $L_a$ .

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Given  $x_0 \in \Gamma(u)$ , define

$$v_{x_0}(x, y) := u(x, y) - \varphi(x, y) - \frac{1}{2s} (-\Delta)^s \varphi(x_0) |y|^{1-a},$$

where  $u(x, y), \varphi(x, y)$  are the  $L_a$ -harmonic extensions of  $u(x)$  and  $\varphi(x)$  from  $\mathbb{R}^n$  to  $\mathbb{R}^n \times \mathbb{R}_+$ .

## Localize our problem

Then

$$\begin{aligned} L_a v_{x_0} &= 0 \text{ on } \mathbb{R}^n \times (\mathbb{R} \setminus \{0\}), \\ v_{x_0} &\geq 0 \text{ on } \mathbb{R}^n \times \{0\}, \\ L_a v_{x_0}(x, y) &\leq h_{x_0}(x) \mathcal{H}^n|_{\{y=0\}} \text{ on } \mathbb{R}^{n+1}, \\ L_a v_{x_0}(x, y) &= h_{x_0}(x) \mathcal{H}^n|_{\{y=0\}} \text{ on } \mathbb{R}^{n+1} \setminus (\{y=0\} \cap \{v_{x_0} = 0\}). \end{aligned} \tag{0.3}$$

where  $h_{x_0}(x) := 2((-\Delta)^s \varphi(x) - (-\Delta)^s \varphi(x_0))$ .

## Optimal regularity

Petrosyan & Pop (2016)

By means of a **new monotonicity formula**, established the optimal  $C^{1,s}(\mathbb{R}^n)$  regularity when  $s \in (1/2, 1)$ ,  $b \in C^s(\mathbb{R}^n; \mathbb{R}^n)$ ,  $0 \leq c \in C^s(\mathbb{R}^n)$ ,  $\hat{\varphi} \in C^{3s}(\mathbb{R}^n) \cap C_0(\mathbb{R}^n)$ .

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Historical background: Almgren's monotonicity formula

The crucial tool introduced to establish the regularity of  $\hat{u}$  is a fundamental **monotonicity formula** proved in 1979 by **F. Almgren**, who showed that if  $\Delta u = 0$  in  $B_1$ , then the **frequency** of  $u$ , given by

$$r \rightarrow N(u, r) = \frac{rD(r)}{H(r)} = \frac{r \int_{B_r} |\nabla u|^2}{\int_{S_r} u^2},$$

is **increasing** in  $(0, 1)$ . Furthermore,  $N(r) \equiv \kappa \iff u$  is homogeneous of degree  $\kappa$ , i.e.,  $u(rx) = r^\kappa u(x)$ .

## Crucial tool in the proof of the optimal regularity

Recall that

$$v_{x_0}(x, y) := u(x, y) - \varphi(x, y) - \frac{1}{2s}(-\Delta)^s \varphi(x_0) |y|^{1-a}$$



## Crucial tool in the proof of the optimal regularity

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Theorem (Monotonicity of the frequency)

Let  $s \in (1/2, 1)$ ,  $\alpha \in (1/2, s)$  and  $x_0 \in \Gamma(u)$ . Then  $\forall p \in [s, \alpha + s - 1/2)$ ,  $\exists C, \gamma, r_0 > 0$  such that  $(0, r_0) \ni r \mapsto e^{Cr^\gamma} \Phi_{x_0}^p(r) \nearrow$ , where

$$\Phi_{x_0}^p(r) := r \frac{d}{dr} \log \max \left\{ \int_{S_r} |v_{x_0}(x_0 + \cdot)|^2 |y|^{1-2s}, r^{n+3+2(p-s)} \right\}$$

Moreover,

$$\Phi_{x_0}^p(0+) \in \left\{ n+3, n+3+2(p-s) \right\} \cup [n+5-2s, \infty).$$

## The regular set

Definition (Regular point for  $u$ )

We say that  $x_0 \in \Gamma(u)$  is *regular* if

$$\Phi_{x_0}^p(0+) = n + 3, \quad \forall p \in (s, 2s - 1/2).$$

We write  $\Gamma_{1+s}(u) := \{x_0 \in \Gamma(u) \mid \Phi_{x_0}^p(0+) = n + 3, \quad \forall p \in (s, 2s - 1/2)\}$ .

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Definition (Regular point for  $\hat{u}$ )

We say that  $x_0 \in \hat{\Gamma}(\hat{u})$  is *regular* if  $x_0 \in \Gamma_{1+s}(u)$  and we denote the set of *regular points of  $\hat{u}$*  as  $\hat{\Gamma}_{1+s}(\hat{u})$ . (So  $\Gamma_{1+s}(u) = \hat{\Gamma}_{1+s}(\hat{u})$ )

## Regularity of the regular part of the free boundary

Garofalo, Petrosyan, Pop & Smit Vega Garcia, 2016:

$\Gamma_{1+s}(u)$  is locally a  $C^{1,\gamma}$ -regular surface. As a consequence, the same result holds for  $\widehat{\Gamma}_{1+s}(\widehat{u})$ .

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$\Gamma_{1+s}(u)$  is locally a  $C^{1,\gamma}$ -regular surface. As a consequence, the same result holds for  $\widehat{\Gamma}_{1+s}(\widehat{u})$ .

Our central results are:

- a new **Weiss type monotonicity formula** and
- a new **epiperimetric inequality**,

both inspired by those originally obtained by Weiss for the classical obstacle problem.

## Spaces

- **Weighted Hölder spaces:** let  $a \in (0, 1)$ ,  $\Omega \subset \mathbb{R}^n \times \mathbb{R}_+$  an open set.  $u \in C^1(\Omega)$  is in  $C_a^{1,\alpha}(\bar{\Omega})$  if

$$\|u\|_{C^\alpha(\bar{\Omega})} + \|u_{x_i}\|_{C^\alpha(\bar{\Omega})} + \||y|^a \partial_y u\|_{C^\alpha(\bar{\Omega})} < \infty.$$

- **Weighted Sobolev space:** let  $U \subset \mathbb{R}^{n+1}$  be a Borel measurable set.  $w \in H^1(U, |y|^a)$  if  $w, Dw \in L^2_{\text{loc}}(U)$  and

$$\int_U (|w|^2 + |\nabla w|^2) |y|^a < \infty.$$

## Outline of our approach

- 1 First main ingredient consists of the “almost monotonicity” of a **Weiss-type functional** which intuitively measures the closeness of the solution  $v$  to the prototypical homogeneous solution of degree  $(1 + s)$ , i.e., the function

$$\left(x_n + \sqrt{x_n^2 + y^2}\right)^s \left(x_n - s\sqrt{x_n^2 + y^2}\right)$$

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The combination of these results provides us with a powerful tool to establish a **geometric rate of decay for the Weiss functional**, which in turn allows us to study the **homogeneous blowups** of  $v$ ,  $v_r(x, y) = \frac{v(rx, ry)}{r^{1+s}}$ , and prove the  $C^{1,\gamma}$  regularity of  $\Gamma_{1+s}(u)$ .



## In more detail

Given  $x_0 \in \Gamma_{1+s}(u)$ , our goals will be to prove that:

- The homogeneous rescalings

$$v_{x_0,r}(x,y) = \frac{v_{x_0}(x_0 + rx, ry)}{r^{1+s}}$$

converge to a (unique) solution of (0.3) with  $h_{x_0}$  substituted by 0, which is **homogeneous of degree  $(1 + s)$** .

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- We can express the unique homogeneous blowup at  $x_0$ ,  $v_{x_0,0}(x,y)$ , as

$$a_{x_0} \left( \langle x, e_{x_0} \rangle + \sqrt{\langle x, e_{x_0} \rangle^2 + y^2} \right)^s \left( \langle x, e_{x_0} \rangle - s \sqrt{\langle x, e_{x_0} \rangle^2 + y^2} \right),$$

for some  $e_{x_0} \in S'_1$ . Moreover,  $v_{x_0,0}$  is **nonzero**.

## In more detail

- To prove  $C^{1,\gamma}$  regularity of  $\Gamma_{1+s}(u)$ :  
 $|a_{\bar{x}} - a_{\bar{y}}| \leq C|\bar{x} - \bar{y}|^\gamma, \quad |e_{\bar{x}} - e_{\bar{y}}| \leq C|\bar{x} - \bar{y}|^\gamma.$

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To obtain the last inequalities we first prove that  $\exists \eta_0 = \eta_0(x_0) > 0$  such that

$$\int_{S_1} |v_{\bar{x},0} - v_{\bar{y},0}| |y|^a \leq C|\bar{x} - \bar{y}|^\gamma \text{ for } \bar{x}, \bar{y} \in B'_{\eta_0}(x_0) \cap \Gamma(u),$$

where  $C$  and  $\gamma > 0$  are universal constants.

## First main ingredient: Weiss type monotonicity formula

Weiss type functional:

$$\begin{aligned} W_L(v, r, x_0) &= W_L(r) \\ &= \frac{1}{r^{n+2}} \left[ \int_{B_r} |\nabla v_{x_0}|^2 |y|^a + \int_{B'_r} v_{x_0} h_{x_0} \right] - \frac{1+s}{r^{n+3}} \int_{S_r} |v_{x_0}(x_0 + \cdot)|^2 |y|^a. \end{aligned}$$

## First main ingredient: Weiss type monotonicity formula

Theorem (Garofalo, Petrosyan, Pop & Smit Vega Garcia, 2016)

Assume  $x_0 \in \Gamma_{1+s}(u)$ . There exists a universal constant  $C > 0$  such that

$$\frac{d}{dr} (W_L(v, r) + Cr^{2s-1}) \geq \frac{2}{r^{n+2}} \int_{S_r} \left( \langle \nabla_{v_{x_0}}, \nu \rangle - \frac{(1+s)v_{x_0}}{r} \right)^2 |y|^a. \quad (0.4)$$

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Hence,  $r \mapsto W_L(v, r) + Cr^{2s-1}$  is  $\nearrow$ , so the following limit exists:

$$W_L(v, 0+) \stackrel{\text{def}}{=} \lim_{r \rightarrow 0} W_L(v, r).$$

## Blow-ups

We recall the definition of the **homogeneous rescallings** of  $v$ :

$$v_r(x, y) = \frac{v(rx, ry)}{r^{1+s}}.$$

### Lemma (Convergence to blow-ups)

Let  $0 \in \Gamma_{1+s}(u)$ . Given  $r_j \rightarrow 0$ ,  $\exists v_0 \in C_{a,\text{loc}}^{1,\alpha}((\mathbb{R}^n)^\pm \cup \{y = 0\})$ ,  $\forall \alpha \in (0, 1)$ , such that

$$v_{r_j} \rightarrow v_0 \text{ in } C_{a,\text{loc}}^{1,\alpha}((\mathbb{R}^n)^\pm \cup \{y = 0\}).$$

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We still do not have: uniqueness of the blow up,  $v_0 \neq 0$  and a rate of convergence of the rescallings to the blow-ups.

## Second main ingredient: Epiperimetric inequality

Let

$$\widehat{v}_0(x, y) := \left( x_n + \sqrt{x_n^2 + y^2} \right)^s \left( x_n - s \sqrt{x_n^2 + y^2} \right).$$

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When  $h_{x_0} \equiv 0$  and  $r = 1$ , our Weiss functional takes an easier form:

$$W_L(v) := W_L(v, 1) = \int_{B_1} |\nabla v|^2 |y|^a - (1 + s) \int_{S_1} v^2 |y|^a d\mathcal{H}^{n-1}.$$

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Theorem (Garofalo, Petrosyan, Pop & Smit Vega Garcia, 2016)

There exists  $\kappa, \theta \in (0, 1)$  such that if  $w \in H^1(B_1, |y|^a)$  is **homogeneous of degree  $(1 + s)$** ,  $w \geq 0$  on  $B'_1$  and  $\|w - \widehat{v}_0\|_{H^1(B_1, |y|^a)} \leq \theta$ , then there exists  $\zeta \in H^1(B_1, |y|^a)$  such that  $\zeta = w$  on  $S_1$ ,  $\zeta \geq 0$  on  $B'_1$  and

$$W_L(\zeta) \leq (1 - \kappa)W_L(w).$$

To recall is to live :)

Recall that our goal is to prove that  $\exists \eta_0 = \eta_0(x_0) > 0$  such that

$$\int_{S_1} |v_{\bar{x},0} - v_{\bar{y},0}| |y|^a \leq C |\bar{x} - \bar{y}|^\gamma \text{ for } \bar{x}, \bar{y} \in B'_{\eta_0}(x_0) \cap \Gamma(u),$$

where  $C$  and  $\gamma > 0$  are universal constants.

## Uniqueness of blowups (for points close to $x_0 \in \Gamma_{1+s}(u)$ )

Let  $r > 0$ ,  $x_0 \in \Gamma_{1+s}(u)$ ,  $v_{x_0,r}(x, y) = \frac{v_{x_0}(x_0 + rx, ry)}{r^{1+s}}$ .

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There exist constants  $r_0 = r_0(x_0)$ ,  $\eta_0 = \eta_0(x_0) > 0$  such that

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Moreover, if  $v_{\bar{x},0}$  is any blow up of  $v$  at  $\bar{x} \in \Gamma(u) \cap B'_{\eta_0}(x_0)$ , then

$$\int_{S_1} |v_{\bar{x},r} - v_{\bar{x},0}| |y|^a \leq Cr^\gamma, \text{ for all } r \in (0, r_0),$$

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Moreover, if  $v_{\bar{x},0}$  is any blow up of  $v$  at  $\bar{x} \in \Gamma(u) \cap B'_{\eta_0}(x_0)$ , then

$$\int_{S_1} |v_{\bar{x},r} - v_{\bar{x},0}| |y|^a \leq Cr^\gamma, \text{ for all } r \in (0, r_0),$$

where  $C > 0$  and  $\gamma \in (0, 1)$  are universal constants. In particular, the blow-up limit  $v_{\bar{x},0}$  is **unique**.

The main ingredient in the proof is the fact that  $W_L(v, r) \leq Cr^\gamma$ , which is proved by using the **epiperimetric inequality**.

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- The unique blowup  $v_{\bar{x},0}$  above is **nonzero**.

## Analysing blowups for $\bar{x}, \bar{y} \in \Gamma(u)$ close to $x_0 \in \Gamma_{1+s}(u)$

### Proposition

Assume  $x_0 \in \Gamma_{1+s}(u)$ . Then, there exists  $\eta_0 = \eta_0(x_0) > 0$  such that

$$\int_{S_1} |v_{\bar{x},0} - v_{\bar{y},0}| |y|^a \leq C |\bar{x} - \bar{y}|^\gamma \quad \text{for } \bar{x}, \bar{y} \in B'_{\eta_0}(x_0) \cap \Gamma(u),$$

where  $C$  and  $\gamma > 0$  are universal constants.

## $C^{1,\gamma}$ regularity of the regular free boundary

Theorem (Garofalo, Petrosyan, Pop & Smit Vega Garcia, 2016)

Let  $s \in (1/2, 1)$ ,  $b \in C^s(\mathbb{R}^n; \mathbb{R}^n)$ ,  $0 \leq c \in C^s(\mathbb{R}^n)$  and  $\hat{\varphi} \in C^{3s}(\mathbb{R}^n) \cap C_0(\mathbb{R}^n)$ . Let  $\hat{u} \in C^{1,s}(\mathbb{R}^n)$  solve (0.1) and  $x_0 \in \hat{\Gamma}_{1+s}(\hat{u})$ . Then  $\exists \gamma \in (0, 1)$  and  $\eta > 0$ , such that

$$B'_\eta(x_0) \cap \hat{\Gamma}(\hat{u}) \subseteq \hat{\Gamma}_{1+s}(\hat{u}),$$

and  $\exists g \in C^{1,\gamma}(\mathbb{R}^{n-1})$ , such that

$$B'_\eta(x_0) \cap \hat{\Gamma}(\hat{u}) = B'_\eta(x_0) \cap \{x_n \leq g(x')\},$$

after a possible rotation in  $\mathbb{R}^n$ .

Thank you!